# MICRO-EH 

PROGRAMMABLE CONTROLLER


## Hitachi's MICRO-EH Series PLC Delivers Various Useful Functions

 for Small Automation Processes!"MICRO-EH is an all-in-one type PLC packed with powerful functions."


High Performance in a Small Size 12-bit analog inputoutput (23-point type)
Two built-in potentiometers (except tor 10-point type)
Buit-in $h$ igh-speed Buill-in high-speed counter
(10/14/23/28-point type : 10 kHz , 20/401/64-point type $: 100 \mathrm{kHz})$ PWM and pulse train output (MICRO-EH with DC output) Maximum 176 I/O points
64 -point type $1+28$-point expansion unit $\times 4$
Flash memory for storing user programs - user program is retained
without battery
Battery for dory Battery for data memory back-up (20/23/288/4/64- point type)
Built-in real-time clock (20/23/28/40/64- point type) Digital filiter
Power supply for sensors
User-friendliness
Removable terminals for easy set-up (except for 10 -point type) Easy installation by snapping on a DIN rail or screwing onto a panel
Easy-to-see terminal layout indication
Compatibllity with H/EH serles PLC Same programming software for utilization of valuable existing user

Conformity to Global Standards CE, UL, c-UL and C-Tick approval
Network Compatibility
S -232C port standard
RS-422/485 port as standard
(up to 32 units connectable)
Environmental Friendliness Laser marking for elimination of sticker type nameplates Battery-less operation for waste reduction

New release

1. 23/28-point type:Extension of program capacity (3k steps $\rightarrow 15.7 \mathrm{k}$ steps). Extension of data memory capacity ( 4,096 words $\rightarrow 32,768$ words).
2. Thermocouple expansion unit
3. 64 points expansion unit.
4. Positioning expansion unit.


Application Examples
Machine Control: Simple positioning control for Cutting Machine


Line Control: Fruit Size Selection


Network Control: Monitoring System with SCADA software


## FEATURES

## High Performance in a Small Size



## (2) 12-bit analog input/output (23-point type)

23-point type has 2 analog inputs and 1 analog output as standard. This feature makes it possible for 23-point type to be connected directly with various sensors and actuators without adding any analog input /output modules. Either voltage or current can be selected at each point. [Input: $0-10 \mathrm{~V}$ or $0-20 \mathrm{~mA}$, Output: $0-10 \mathrm{~V}$ or $0-20 \mathrm{~mA}$ ]

This feature can be applied to a pump system for reservoirs using water level sensors.


## (2) Two built-in potentiometers (except for 10-point and 20/40/64-point type)

Timer constant value can be easily changed using these potentiometers even if you do not have a programming device.
Values set by the potentiometers are always reflected in the special internal output. Smoothing is possible for these values.
[The value of the potentiometer 1 and 2 are stored in WRF03E and WRF03F respectively.] [Smoothing: to average the value that varies with time by dividing the specified value.] [The timer value must be set by a variable in advance.]

With these potentiometers, operation interval can be tuned easily.


## e Potentiometers

## - The FLASH memory which protects a user's program

FLASH memory for backup of a user's program.
The user program is stored in FLASH memory so that the user program can be retained in case
the battery goes dead.
If user program are changed frequently, the lifetime of FLASH memory will be shorter.
3 Please refer to the application manual about the times over writing to FLASH memory.

## Built-in high-speed counter

A high-speed counter is provided as standard eliminating the need for an additional counter module for high-speed applications.
14/23/28-point type with DC input can count up to 1-phase
4 channels.
14/23/28-point type: Max.10kHz
20/40/64-point: Max.100kHz
Select one mode from:
1-ph 4ch, 2ph 2ch, or 2-ph 1ch+1-ph 2ch [20/40/64-point] 1 -ph 4 ch, 1 -ph 2ch, or 2 -ph 1ch +1 -ph 1 ch [14-/23-/28-point] 1 -ph 3ch, 1-ph 2ch, or 2-ph 1ch [10-point]
By taking input directly from an external encoder, the position of the object being controlled can be detected.
[The functions that can be used (pulse train, PWM, interruption input, etc.) vary in each mode.]
This feature can be applied to the detection of the position of objects on various assembly, processing, and testing lines.


## (2) PWM and pulse train output

 (MICRO-EH with DC output)PWM output is provided as standard.


Temperature control and light brightness control are possible by modulating the pulse width. 10/14/23/28-point:up to $2 \mathrm{kHz} \quad 20 / 40 / 64$-point:up to 65 kHz Pulsetrain outputis also prorided as standard

Simple positioning control, fine tuning of conveyor's moving distance, etc. are possible by pulse train output with acceleration/deceleration function. 10/14/23/28-point:Max.5kHz 20/40/64-point:Max.65kHz

## NEW (7) Maximum 320 I/O points (64-point type x1 + 64-point expansion unit x4)

Up to 4 expansion units can be connected. (except for 10-point type)
Cable length is up to 2 m eters in total.

## (7) Flash memory for storing user programs

To protect valuable programs from being erased during power failure, the MICRO-EH contains flash memory for storing user programs.

## Battery for data memory back-up (20/23/28/40/64-point type)

An optional battery is mountable for data memory back-up.

## (2) Built-in real-time clock (20/23/28/40/64-point type)

A real-time clock is provided as standard (20/23/28/40/64-point type) for event scheduling.

## (2) Digital filter

Filtering delay time can be adjusted to eliminate chattering. It can be set between 0 and 20 ms in units of 0.5 ms .

Power supply for sensors (14/20/23/28/40/64-point type and 14/28-point expansion unit)
The 24 V terminal at the input terminal block can supply current to external equipment. [When this power is used as the power supply for the input part of the MICRO-EH, the remaining power can be used for sensors.]

## User-friendliness

## Removable terminals for easy set up

 (except for 10-point type)Replacement of the MICRO-EH can be accomplished in a fraction of the time.

## Easy installation by snapping on a DIN rail or screwing onto a panel



Terminal protective covers are hinged and can stay open for easy wiring.
Terminal layout indication on the front panel can be read even when the

Benters Compatibility with H/EH series PLC

Same programming software for utilization of valuable existing user programs -LADDER EDITOR for Windows ${ }^{\circledR}$
[Pro-H (IEC61131-3) is also available.]

## LADDER EDITOR for Windows ${ }^{\circledR}$

Windows is a registered trademark of Microsoft Corp. in the U.S. and other countries.
Conformity to Clobal Standards
CE, UL, c-UL and C-Tick approvals


Please refer to P28-29 for details.

## Network Compatibility

## RS-232C port as standard (Port 1)

Communication speed can be selected from 4800, 9600, 19200, and 38400 bps.*1
Modem control function is incorporated. (except for 10-point type)

* 1: Communication speed for 10 -point type is fixed at 4800 bps.


By connecting the port 1 with a peripheral unit, the created programs can be transferred, the programs stored in the CPU can be read/verified, and CPU operating status can be monitored. In addition, a monitoring system that connects the display device, etc. can be configured.

## (3) RS-422/485 port as standard for 23/28-point type (port 2)

Either RS-422 or RS-485 can be selected by the connection wiring.


1:n station communication by HI-PROTOCOL is possible via the port $2^{* 2}$. By creating and including a control procedure based on HI-PROTOCOL on the personal computer that will become the host, it is then possible to control 32 units from one host.


* 2: When performing 1:n station communication using port 2, the transmission control procedure that can be used is restricted by the interface. Since transmission and reception are started up at the same time in transmission control procedure 2, it is not possible to perform communication with an RS-485 interface. The table shown right reflects the correspondence between transmission control procedure and interface.

|  |  | RS-422 | RS-485 |
| :--- | :---: | :---: | :---: |
| Transmission control <br> procedure 1 | $1: 1$ | Possible | Possible |
| Transmission control <br> procedure 2 | $1: 1$ | Possible | Possible |
|  | 1:n | Possible | Impossible |

## Option Communication board for 20/40/64-point type

With RS-232C or RS-422/485 or USB-232C convertion communication board communication port2 can be used as a programming port or a general-purpose port.

## Option Memory board for 20/40/64-point type

With Memory board, it can be used for backup of a user program etc.

## Environmental Friendliness

Laser marking system is employed for the MICRO-EH series to eliminate sticker type nameplates.
ABS material is used for outer case of the MICRO-EH for easy recycling.
Battery-less operation with flash memory helps reduce waste.

## SYSTEM GONFIGURATION

## 10-point Type

## 6 inputs and 4 outputs (not expandable) 10-point type MICRO-EH can be easily mounted on machines or equipment thanks to its small size ( $\mathrm{D}: 47 \mathrm{~mm}$ ).

PROGRAMMABLE CONTROLEE

POW- io: $_{4}^{23}$ EH-D10DTP

## 14/20/23/28/40/64-point Type

## NEW Maximum 4 expansion units can be connected to each type.

-14-point type: Maximum 168 inputs and 102 outputs (4 expansion units), 270 points in total
■20-point type: Maximum 172 inputs and 104 outputs (4 expansion units), 276 points in total
■23-point type: Maximum 173 inputs and 106 outputs (4 expansion units), 279 points in total
-28-point type: Maximum 176 inputs and 108 outputs (4 expansion units), 284 points in total
40-point type: Maximum 184 inputs and 112 outputs (4 expansion units), 296 points in total
■64-point type: Maximum 200 inputs and 120 outputs (4 expansion units), 320 points in total


## Cable length: Max. 2 m in total



## - Three different lengths of expansion cable are available.

[^0]Maximum cable length between the basic unit and the expansion unit is 2 m .

Functional Specifications

| Item |  | 10-point type | 14-point type | 20-point type | 23-point type | 28-point type | 40-point type | 64-point type |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RS-232C port |  | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| RS-422/485 port |  | - | - | 1(Optinal) | 1 | 1 | 1(Optinal) | 1(Optinal) |
| High-speed counter |  | 10 kHz <br> 1-phace 3ch, <br> 1-phace 2ch or 2-phace 1ch | 10kHz <br> 1-phace 4ch, <br> 1-phace 2ch or 2-phace 1ch +1 phace 1ch | 100kHz <br> 1-phace 4ch, <br> 2-phace 2ch or 2-phace 1ch +1 phace 2 ch | 10kH <br> 1-phace 4ch, or 2-phace 1ch | phace 2ch phace 1ch | or 2-phace 1c | $\begin{aligned} & -1 z \\ & 4 \mathrm{ch} \\ & 2 \mathrm{ch} \\ & \text { 1phace 2ch } \end{aligned}$ |
| Interruption input |  | 3 points | 4 points |  |  |  |  |  |
| PWM output |  | $\begin{gathered} \mathbf{2 k H z} \\ (\text { in total }) \end{gathered}$ |  | 65 kHz (each channel) | $\underset{(\text { in total })}{\mathbf{2 k H z}}$ |  | 65 kHz (each channel) | 65 kHz (each channel) |
| Pulse train |  | $\stackrel{5 \mathrm{kHz}}{(\text { in total })}$ |  | 65 kHz (each channel) | 5 kHz (in total) |  | 65 kHz (each channel) | 65 kHz (each channel) |
| Analog input |  | 8-bit : 1ch *1 | - | - |  | - | - | - |
| Analog output |  | - | - | - | 12 bit: $2 \operatorname{ch}(0-10 \mathrm{~V}$ or $0-20 \mathrm{~mA})$ 12 bit: $1 \operatorname{ch}(0-10 \mathrm{~V}$ or $0-20 \mathrm{~mA})$ | - | - | - |
| Potentiometer |  | - | 10-bit : 2ch | - | 10-bit : 2ch |  | - | - |
| Battery(optional) |  | - | - | EH-MBATL | EH-MBAT or EH-MBATLC |  | EH-MBATL |  |
| Real-time clock |  | - | - | Yes | Yes | Yes | Yes | Yes |
| Digital filter |  | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Power source | AC100/200V | No | Yes | Yes | Yes | Yes | Yes | Yes |
|  | DC24V | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Input | DC | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
|  | AC | No | Yes | No | No | Yes | No | No |
| Output | TR DC24V | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
|  | RY | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
|  | SSR | No | Yes | No | No | Yes | No | No |
| Positioning expansion |  | No | No | Yes | Yes | Yes | Yes | Yes |

## ※1: EH-D10DRA only

## CONNEGTION WITH PERIPHERAL EQUIPMENT

MICRO-EH


Windows is a registered trademark of Microsoft Corp. in the U.S. and other countries.

# New release of 20/40/64-point type 

## Built-in high-speed counter (4ch Max.100kHz 32bits) as standard. MICRO-EH 20/40/64-point type.

## 20/40/64-point unit

## I/O points is up

20-point type : Input 12 points, Output 8 points 40-point type : Input 24 points, Output 16 points 64 -point type : Input 40 points, Output 24 points


## User program memory, Data memory is up.

Program capacity is extended to 16 k steps, and data memory capacity is extended to 32 k words, which enables 64-point type to support middle range

## New FUN commands

54 kinds of commands are added. The added FUN commands are a data conversion command, a floating point arithmetic, etc.

## User program memory

20/40/64-point type


Data memory
20/40/64-point type
32k words

10-28-point type $\square$

## 4ch, 100kHz, 32 bits high-speed counter

The counter of 20/40/64-point type can support up to 100 kHz (single phase) or 60 kHz (2-phase ) pulses. The 16 -bit counter is extended to the 32 -bit counter.


## Pulse train output

A pulse output with an output frequency of 65 kHz is possible for 20/40/64-point type. Moreover, the number of output pulses can be set up by 32 bits.

Pulse train output

20/40/64-point type
65 kHz 32 bits (each channel)

10-28-point type
5 kHz (total) 16 bits

## PWM output

20/40/64-point type
65 kHz (each channel)

10-28-point type
2 kHz (total)

## Selectable option boards

A function is expandable by attaching an option board In a basic unit.
With RS-232C or RS-422/485 or USB-232C convertion communication board, communication port 2 can be used as an programming port or a general-purpose port. With Memory board, it can be used for backup of a user program etc.
A communication board and a memory board can be used together.

PID function


PID function is supported by 20/40/64-point unit.

## PRODUGT SPECIFICATIONS

## 10/14/23/28-point type CPU Specifications

| $$ | Name |  |  | 10-point type | 14-point type | 23-point type | 28-point type |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | CPU |  |  |  |  |  |  |
|  | Processing system |  |  | Stored program cyclic system |  |  |  |
|  | Processing speed | Basic instructions |  | $0.9 \mu \mathrm{~s} /$ instruction |  |  |  |
|  |  | Application instructions |  | Several $10 \mu \mathrm{~s} /$ instruction |  |  |  |
|  | User program memory |  |  | 3 k steps max. (FLASH memory) |  | 16 k steps max. (FLASH memory) |  |
| Operation processing specifications | Instruction language | Basic instructions |  | 39 types such as LD, LDI, AND, ANI, OR, ORI, ANB, ORB, OUT, MPS, MRD, MPP, etc. |  |  |  |
|  |  | Arithmetic instructions Application instructions |  | 62 types (arithmetic, application, control, FUN command etc.) |  |  |  |
|  | Ladder | Basic instructions |  |  |  | ch as | -1 |
|  |  | Arithmetic instructions Application instructions |  | 62 types (arithmetic, application, control, FUN command etc.) |  |  |  |
| I/O processing specifications | External I/O | I/O processing system |  | Refresh processing |  |  |  |
|  |  | Maximum number of points |  | 10 points | 126 points | 135 points | 140 points |
|  | Internal output | Bit |  | 1,984 points (R0 to R7BF) |  |  |  |
|  |  | Word |  | 4,096 wo | 0 to WRFFF) | 32,768 words (WR0 to WR7FFF) |  |
|  |  | Special | Bit | 64 points (R7C0 to R7FF) |  |  |  |
|  |  |  | Word |  | 512 words ( | to WRF1FF) |  |
|  |  | Bit/word shared |  | 16,384 points, 1,024 words (M0 to M3FFF, WM0 to WM3FF) |  |  |  |
|  | Timer counter | Number of points |  | 256 points (TD + CU) *1 |  |  |  |
|  |  | Timer set value |  | 0 to 65,535 , timer base $0.01 \mathrm{~s}, 0.1 \mathrm{~s}, 1 \mathrm{~s}$ (0.01s has maximum 64 points *2) |  |  |  |
|  |  | Counter set value |  | 1 to 65,535 times |  |  |  |
|  | Edge detection |  |  | $\begin{aligned} & 512 \text { points (DIF0 to DIF511: Decimal) } \\ & +512 \text { points (DFN0 to DFN511: Decimal) } \end{aligned}$ |  |  |  |
|  | Program system |  |  | Instruction language, ladder diagram |  |  |  |
| Peripheral equipment | Peripheral unit |  |  | Programming software (LADDER EDITOR DOS version/Windows ${ }^{\circledR}$ version, Pro-H) Instruction language programmer and form graphic display programmer cannot be used. |  |  |  |
| Maintenance functions | Self-diagnosis |  |  | PLC error (LED display): Microcomputer error, watchdog timer error, memory error, program error, system ROM/RAM error, scan time monitoring, battery voltage low detection, etc. |  |  |  |

[^1]
## 10/14/23/28-point type Input/Output Specifications

Input/Output specification and points of Basic unit (Onumber corresponds to the number of table of specification.)

| Type | Model Name | Power |  | Input | Input | Point | Output | Output Point |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 24 V DC | $\begin{array}{\|c\|} \hline 100 / 200 \mathrm{~V} \\ \text { AC } \end{array}$ |  | 24 V DC | $\begin{gathered} \text { 100/200V } \\ \text { AC } \end{gathered}$ |  | Relay <br> Output | Transistor Output |  | Transistor Output (source ESCP) |  | Transistor | SSR |
|  |  |  |  |  |  |  |  |  | Low Current | High Current | Low Current | High Current | Output(source) |  |
|  |  |  |  |  | (1) | (4) |  | (5) | (7) | (8) | (9) | (10) | (11) | (13) |
| 10 Points | EH-D10DT | $\bigcirc$ |  | 24 V DC $\times 6$ | 6 (1) |  | Transistor $\times 4$ (sink) |  | 4 (1) |  |  |  |  |  |
|  | EH-D10DTP | $\bigcirc$ |  | 24 V DC $\times 6$ | 6 (1) |  | Transistor $\times 4$ (source) |  | 4 (1) |  |  |  |  |  |
|  | EH-D10DR | $\bigcirc$ |  | 24 V DC $\times 6$ | 6 (1) |  | Relay $\times 4$ | 4 (1) |  |  |  |  |  |  |
| 14 Points | EH-D14DT | $\bigcirc$ |  | 24 V DC $\times 8$ | 8 (2)[4,4] |  | Transistor $\times 6$ (sink) |  | 4 (1) | 2 |  |  |  |  |
|  | EH-D14DTP | $\bigcirc$ |  | 24 V DC $\times 8$ | 8 (2)[4,4] |  | Transistor $\times 6$ (source) |  | 4 (1) | 2 |  |  |  |  |
|  | EH-D14DTPS | $\bigcirc$ |  | 24 V DC $\times 8$ | 8 (2)[4,4] |  | Transistor (source ESCP) $\times 6$ |  |  |  | 4 (1) | 2 |  |  |
|  | EH-D14DR | $\bigcirc$ |  | 24 V DC $\times 8$ | 8 (2)[4,4] |  | Relay $\times 6$ | 6 (3)[1,1,4] |  |  |  |  |  |  |
|  | EH-A14DR |  | $\bigcirc$ | 24 V DC $\times 8$ | 8 (2)[4,4] |  | Relay $\times 6$ | 6 (3)[1,1,4] |  |  |  |  |  |  |
|  | EH-A14AS |  | $\bigcirc$ | AC $\times 8$ |  | $8(2)[4,4]$ | SSR $\times 6$ |  |  |  |  |  |  | $6(2)[2,4]$ |
| 23 Points | EH-D23DRP | $\bigcirc$ |  | $\begin{gathered} 24 \mathrm{~V} \text { DC } \times 13 \\ \text { Analog } \times 2 \text { (12bits) } \end{gathered}$ | $\begin{aligned} & 13(3) \\ & {[4,4,5]} \end{aligned}$ |  | Relay $\times 9$ Transistor $\times 1$ (source) Analog 1 (12bits) | $\begin{gathered} 9(5) \\ {[4,1,1,1,2]} \end{gathered}$ |  |  |  |  | 1 (1) |  |
|  | EH-A23DRP |  | $\bigcirc$ | $\begin{gathered} 24 \mathrm{~V} \text { DC } \times 13 \\ \text { Analog } \times 2(12 \text { bits }) \end{gathered}$ | $\begin{gathered} 13(3) \\ {[4,4,5]} \end{gathered}$ |  | $\begin{gathered} \text { Relay } \times 9 \\ \text { Transistor } \times 1 \text { (source) } \\ \text { Analog } 1 \text { (12bits) } \\ \hline \end{gathered}$ | $\begin{gathered} 9(5) \\ {[5,1,1,1,2]} \end{gathered}$ |  |  |  |  | 1 (1) |  |
|  | EH-A23DR |  | $\bigcirc$ | 24V DC $\times 13$ Analog $\times 2$ (12bits) | $\begin{aligned} & 13(3) \\ & {[4,4,5]} \end{aligned}$ |  | $\begin{gathered} \text { Relay } \times 10 \\ \text { Analog } 1 \text { (12bits) } \end{gathered}$ | $\begin{gathered} 10(6) \\ {[1,4,1,1,1,2]} \end{gathered}$ |  |  |  |  |  |  |
| 28 points | EH-D28DT | $\bigcirc$ |  | 24 V DC $\times 16$ | $\begin{gathered} 16(4) \\ {[4,4,4,4]} \end{gathered}$ |  | Transistor $\times 12$ (sink) |  | 8 (2)[6,6] | 4 |  |  |  |  |
|  | EH-D28DTP | $\bigcirc$ |  | 24 V DC $\times 16$ | $\begin{gathered} 16(4) \\ {[4,4,4,4]} \end{gathered}$ |  | Transistor $\times 12$ (source) |  | 8 (2)[6,6] | 4 |  |  |  |  |
|  | EH-D28DTPS | $\bigcirc$ |  | 24 V DC $\times 16$ | $\begin{gathered} 16(4) \\ {[4,4,4,4]} \end{gathered}$ |  | $\begin{gathered} \text { Transistor } \\ \text { (source ESCP) } \times 12 \end{gathered}$ |  |  |  | 8 (2)[6,6] | 4 |  |  |
|  | EH-D28DRP | $\bigcirc$ |  | 24 V DC $\times 16$ | $\begin{gathered} 16(4) \\ {[4,4,4,4]} \end{gathered}$ |  | $\begin{gathered} \text { Relay } \times 11 \\ \text { Transistor } \times 1 \text { (source) } \end{gathered}$ | $\begin{gathered} 11(6) \\ {[4,1,1,1,1,3]} \end{gathered}$ |  |  |  |  | 1 (1) |  |
|  | EH-D28DR | $\bigcirc$ |  | 24 V DC $\times 16$ | $\begin{gathered} 16(4) \\ {[4,4,4,4]} \end{gathered}$ |  | Relay $\times 12$ | $\begin{gathered} 12(7) \\ {[1,4,1,1,1,1,1,3]} \end{gathered}$ |  |  |  |  |  |  |
|  | EH-A28DRP |  | $\bigcirc$ | 24 V DC $\times 16$ | $\begin{gathered} 16(4) \\ {[4,4,4,4]} \end{gathered}$ |  |  | $\begin{gathered} 11(6) \\ {[4,1,1,1,1,3]} \end{gathered}$ |  |  |  |  | 1 (1) |  |
|  | EH-A28DR |  | $\bigcirc$ | 24 V DC $\times 16$ | $\begin{gathered} 16(4) \\ {[4,4,4,4]} \end{gathered}$ |  | Relay $\times 12$ | $\begin{gathered} 12(7) \\ {[1,4,1,1,1,1,3]} \end{gathered}$ |  |  |  |  |  |  |
|  | EH-A28AR |  | $\bigcirc$ | AC $\times 16$ |  | $\begin{gathered} 16(4) \\ {[4,4,4,4]} \\ \hline \end{gathered}$ | Relay $\times 12$ | $\begin{gathered} 12(7) \\ {[1,4,1,1,1,1,1,3]} \end{gathered}$ |  |  |  |  |  |  |
|  | EH-A28AS |  | $\bigcirc$ | AC $\times 16$ |  | $\begin{gathered} 16(4) \\ {[4,4,4,4]} \end{gathered}$ | SSR $\times 12$ |  |  |  |  |  |  | $\begin{gathered} 12(4) \\ {[2,4,2,4]} \end{gathered}$ |

The value of ( ): number of common. The value of [ ]:number of I/O points to each common.
Input/Output specification and points of Expasion unit (Cnumber corssponds to the number of toble of specificioion.)


[^2]
## (1)DC input (Basic units)

| Item |  | Specification | Circuit diagram |
| :---: | :---: | :---: | :---: |
| Input voltage |  | 24 V DC |  |
| Allowable input voltage range |  | 0 to 30 V DC |  |
| Input impedance |  | Approx. $2.8 \mathrm{k} \Omega$ | $\square 0$ |
| Input current |  | Approx. 7.5 mA |  |
| Operating | ON voltage | $15 \mathrm{VDC}(\mathrm{min}) / 4.5 \mathrm{~mA}(\max )$ |  |
| voltage | OFF voltage | 5 V DC (max) / $1.5 \mathrm{~mA}(\max )$ |  |
| Input lag | OFF $\rightarrow$ ON | 0.5 to 20 ms (configurable) |  |
|  | ON $\rightarrow$ OFF | 0.5 to 20 ms (configurable) |  |
| Polarity |  | None |  |
| Insulation system |  | Photocoupler insulation |  |
| External connection |  | 10-point type: fixed type terminal block 14/23/28-point types: Removable type screw terminal block (M3) | $1$ |

*1: Common terminals are separated each other.

## (2)DC input (Expansion units)

| Item |  | Specification | Circuit diagram |
| :---: | :---: | :---: | :---: |
| Input voltage |  | 24 V DC |  |
| Allowable input voltage range |  | 0 to 30 V DC |  |
| Input impedance |  | Approx. $2.8 \mathrm{k} \Omega$ |  |
| Input current |  | Approx. 7.5 mA |  |
| Operating voltage | ON voltage | $15 \mathrm{~V} \mathrm{DC}(\mathrm{min}) / 4.5 \mathrm{~mA}(\max )$ |  |
|  | OFF voltage | 5 V DC ( $\max$ ) / 1.5 mA (max) |  |
| Input lag | $\xrightarrow{\text { OFF } \rightarrow \text { ON }}$ | 0.5 ms or less |  |
| Polarity |  | None |  |
| Insulation system |  | Photocoupler insulation |  |
| Input display |  | LED (green) |  |
| External connection |  | 10-point type: fixed type terminal block 14/23/28-point types: Removable type screw terminal block (M3) |  |

*1: Common terminals are separated each other.

## (3)DC input (8points / $16 p o i n t s$ expansion units)

| Item |  | Spec | cation | Circuit diagram |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | EH-D8EDR EH-D8EDTPS EH-D8EDT | $\begin{aligned} & \text { EH-D8ED } \\ & \text { EH-D16ED } \end{aligned}$ |  |  |  |
| Input voltage |  | 24 V DC |  |  |  |  |
| Allowable input voltage range |  | 0 to 30 V DC |  |  |  |  |
| Input impedance |  | Approx. $2.8 \mathrm{k} \Omega$ | Approx. $4.8 \mathrm{k} \Omega$ |  |  |  |
| Input current |  | Approx. 7.5 mA | Approx. 4.8 mA |  |  |  |
| Operating voltage | ON voltage | $15 \mathrm{VDC}($ min $) / 4.5 \mathrm{~mA}($ max $) 15 \mathrm{VDC}($ min $) / 3.0 \mathrm{~mA}($ max $)$ |  |  |  |  |
|  | OFF voltage | 5 V DC (max) / 1.5 mA (max) |  |  |  |  |
| Input lag | OFF $\rightarrow$ ON | $4 \mathrm{~ms} \mathrm{(TYP)}$ | 2ms(TYP) |  |  |  |
|  | ON $\rightarrow$ OFF | $4 \mathrm{~ms} \mathrm{(TYP)}$ | $2 \mathrm{~ms} \mathrm{(TYP)}$ |  |  |  |
| Polarity |  | None |  |  |  |  |
| Insulation system |  | Photocoupler insulation |  |  |  |  |
| Input display |  | LED (green) |  |  |  |  |
| External connection |  | Removable type screw terminal block(M3) |  |  |  |  |

(4)AC input


Item
Rated load voltage
Minimum switching current
Leak current

| $\begin{array}{l}\text { Maximum } \\ \text { load current }\end{array}$ | 1 circuit |
| :--- | :--- |
|  | 1 common |


| $\begin{array}{l}\text { Output } \\ \text { response time }\end{array}$ | $\mathrm{OFF} \rightarrow$ ON |
| :--- | :--- |
|  | $\mathrm{ON} \rightarrow$ OFF |

Surge removing circuit
Fuse
Insulation system
Output display
Externally supplied power
(for driving the relays)
Contact life
Insulation
20,000,000 times (mechanical)
200,000 times (electrical: 2 A )
$1,500 \mathrm{~V}$ or more (external-internal)
500 V or more (external-external)
Removable type screw terminal block
(M3)
5 to 250 V AC, 5 to 30 V DC 10 mA
15 mA or less
2 A (24 V DC, 240 V AC$)$
5 A

ms (max)
None None

| Specification |
| :---: |
| 5 to $250 \mathrm{~V} \mathrm{AC}, 5$ to 30 V DC |
| 10 mA |
| 15 mA or less |
| $2 \mathrm{~A}(24 \mathrm{~V} \mathrm{DC}, 240 \mathrm{~V} \mathrm{AC})$ |
| 5 A |
| 15 ms (max) |
| 15 ms (max) |
| None |
| None |
| Relay insulation |
| LED (green) |
| Not necessary |
| $20,000,000$ times (mechanical) |
| $200,000$ times (electrical: 2 A$)$ |
| $1,500 \mathrm{~V}$ or more (external-internal) |
| 500 V or more (external-external) |
| Removable type screw terminal block |
| (M3) |

external connection

(6Relay output (8points / 16points expansion unit)

| Item | Specification | Circuit diagram |  |
| :---: | :---: | :---: | :---: |
| Rated load voltage | 5 to 250 V AC, 5 to 30 V DC |  |  |
| Minimum switching current | 1 mA |  |  |
| Leak current | 15 mA or less |  |  |
| Maximum load current | $2 \mathrm{~A}(24 \mathrm{~V}$ DC, 240 V AC) |  |  |
|  | 5 A |  |  |
| Output response time | 15 ms (max) |  | 10 |
|  | 15 ms (max) |  | $\left.\bigcirc\right\|_{0} ^{0} 0$ |
| Surge removing circuit | None |  | I |
| Fuse | None |  |  |
| Insulation system | Relay insulation |  |  |
| Output display | LED (green) |  |  |
| Externally supplied power (for driving the relays) | Not necessary |  |  |
| Contact life | 20,000,000 times (mechanical) 200,000 times (electrical: 1.5 A) |  |  |
| Insulation | $1,500 \mathrm{~V}$ or more (external-internal) 500 V or more (external-external) |  |  |
| External connection | Removable type screw terminal block (M3) |  |  |

(7)DC Transistor output: LCDC-Low Current


## (8DC Transistor output: HCDC-High Current

| Item | Specification | Circuit diagram |  |
| :---: | :---: | :---: | :---: |
| Rated load voltage | 24/12 V DC (+10 \%, -15 \%) | Sink type Vo |  |
| Minimum switching current | 1 mA |  |  |
| Leak current | 0.1 mA (max) |  |  |
| Maximum 11 circuit | 1A/24 V DC |  | Source type Vo |
| load current 1 common | 3 A |  |  |
| Output response time | 0.1 ms (max) 24 V DC 0.2A |  |  |
|  | 0.1 ms (max) 24 V DC 0.2A |  |  |
| Surge removing circuit | None |  | इ $\quad \mid \stackrel{\vdash}{\mapsto}$ |
| Fuse | None |  |  |
| Insulation system | Photocoupler insulation |  |  |
| Output display | LED (green) |  |  |
| Externally supplied power | 30 to 12 V DC |  |  |
| Insulation | $1,500 \mathrm{~V}$ or more (external-internal) 500 V or more (external-external) |  |  |
| Output voltage drop | 0.3 V DC (max) |  |  |
| External connection | Removable type screw terminal block (M3) |  |  |

## (9)DC Transistor output (ESCP type): LCDC-Low Current


(10DC Transistor output (ESCP type): HCDC-High Current

| Item |  |
| :--- | :--- |
| Rated load voltage |  |
| Minimum switching current |  |
| Leak current |  |
| Maximum <br> load current | 1 circuit |
| Output <br> response time | OFF $\rightarrow$ ON |
|  | ON OFF |
| Surge removing circuit |  |
| Fuse |  |
| Insulation system |  |
| Output display |  |
| Externally supplied power |  |
| Insulation |  |
| Output voltage drop |  |
| External connection |  |


| Specification |
| :---: |
| 24/12 V DC (+10 \%, -15 \%) |
| 10 mA |
| 0.1 mA (max) |
| 1 A |
| 3 A |
| 0.05 ms (max) 24 V DC 0.2A |
| 0.05 ms (max) 24 V DC 0.2A |
| None |
| None |
| Photocoupler insulation |
| LED (green) |
| 30 to 12 V DC |
| $1,500 \mathrm{~V}$ or more (external-internal) 500 V or more (external-external) |
| 0.3 V DC (max) |
| Removable type screw terminal block (M3) |

Circuit diagram

Source type (ESCP)


## (11)DC Transistor output (Source type)

| Item | Specification |
| :---: | :---: |
| Rated load voltage | $\begin{gathered} 24 / 12 / 5 \vee D C \\ 24 \vee D C+20 \%,-80 \% \end{gathered}$ |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA (max) |
| Maximum load current | 0.75 A/24 V DC 0.5 A/12 V DC 0.25 A/5 V DC |
|  | 0.75 A |
| Output response time | 0.1 ms (max) 24 V DC 0.2 A |
|  | 0.1 ms (max) 24 V DC 0.2 A |
| Surge removing circuit | None |
| Fuse | None |
| Insulation system | Photocoupler insulation |
| Output display | LED (green) |
| Externally supplied power to V terminal | 30 to 16 V DC |
| Insulation | $1,500 \mathrm{~V}$ or more (external-internal) 500 V or more (external-external) |
| Output voltage drop | 0.3 V DC (max) |
| External connection | Removable type screw terminal block (M3) |

## Circuit diagram



## (12)DC Transistor output

| Item | Specification |
| :--- | :---: | :---: |
| sink type |  |

## (13)AC output (SSR)

| Item | Specification |
| :--- | :---: |
| Rated voltage | $100 / 240 \mathrm{~V} \mathrm{AC}$ |
| Output voltage | $100-15 \%$ to $240+10 \% \mathrm{~V} \mathrm{AC}$ |
|  | $50-5 \%$ to $60+5 \% \mathrm{~Hz}$ |$]$

## -


*1: It is necessary to repair the module if the load short-circuits and causes the fuse to melt. Note that the fuse cannot be replaced by users.

## Analogue Input Specifications



## Analogue Output Specifications

| Module type | 23 points type module | Analog expansion unit |
| :---: | :---: | :---: |
| Output channel | 1 ch | 2 ch |
| Output range | 0-10V (10.24V max.) | 0-10V (10.24V max.) |
|  | 0-20mA (20.48mA max.) | 0-20mA (20.48mA max.) |
|  | - | 4-20mA (20.38mA max.) |
| Resolution | 12 bits |  |
| Accuracy | $\pm 1$ \% of full scale |  |
| Current output | 10 to $500 \Omega$ <br> Maximum 2,000 pF <br> Maximum 1 H |  |
| Allowable load |  |  |
| Output allowable capacity |  |  |
| Output allowable inductance |  |  |
| Voltage output |  |  |
| Allowable load | Minimum $10 \mathrm{k} \Omega$ <br> Maximum $1 \mu \mathrm{~F}$ |  |
| Output allowable impedance |  |  |

## High-Speed Gounter Specifications



Since 10 points type does not have input X6, counter channel is up to 3 ch.

## PWW OutputPulse Train Output Specifications

|  | 23-point and 28-point type Relay Output | 10/14/28-point Transistor Output |
| :---: | :---: | :---: |
| Available outputs | Y100 (optional) | Y100-Y103 (optional) |
| Load voltage | 5/12/24 V | $12 / 24 \mathrm{~V}$ |
| Minimum load current | 1 mA |  |
| PWM max. output frequency *1 | 2 kHz total |  |
| Pulse train max. output frequency ${ }^{\text {*1 }}$ | 5 kHz total |  |

1: Relay outputs cannot keep up with high frequencies; these outputs should be used at the operating frequency upon confirmation.

## RTD Input Specifications


*Note : The max. cable length is 100 m , however it depends on noise environment or other conditions.

## Potentiometer Analogue Input Specilications

Number of potentiometer inputs
Input range
Resolution
Input filter

```
    2
0-1023 (H0-H3FF)
    10 bits
    By user settings
```


## Interiupt Input Specilications

## Input that can be used

| Input voltage | ON |
| :--- | :--- |
|  | OFF |

## $\mathrm{X} 1, \mathrm{X} 3, \mathrm{X} 5, \mathrm{X} 7$ (by user settings)

15 V
5 V

## 20/40/64 points type InputOutput Specifications

## 20/40/64-point type CPU Specifications

| Specification | Item |  |
| :---: | :---: | :---: |
| Control Spec. | CPU |  |
|  | Processing system |  |
|  | Processing | Basic Application |
|  | Speed |  |
|  | User program memory |  |
| Operation Spec. | Instruction language | Basic instructions |
|  |  | Arithmetic instructions Application instructions |
|  | Ladder | Basic |
|  |  | Arithmetic instructions Application instructions |
| I/0 processing Spec. | External I/O | I/O processing system Max. number of points |
|  |  |  |
|  | Internal output | Bit |
|  |  | Word |
|  |  | Special Bit |
|  |  | Word |
|  |  | BitWord shared |
|  | Timer / counter | Number of points |
|  |  | Timer set value |
|  |  | Counter set value |
|  | Edge detection |  |
| Peripheral equipment | Program system |  |
|  | Peripheral unit |  |
| Maintenance functions | Self-diagnosis |  |

20/40/64-point type
32-bit RISC processor
Stored program cyclic system
0.9 ss / instruction
Several $10 \mu \mathrm{Hs} /$ instruction $^{16 \mathrm{ksteps} \text { max. (FLASH memory) }}$
39 types such as LD, LDI, AND, ANI, OR, ORI, ANB, ORB, OUT,
MPS, MRD, MPP, etc.
*1 The same numbers cannot be shared by the timer and the counter. TD is 0 to 255 .
*2 Only timers numbered 0 to 63 can use 0.01 s for their time base.
20/40/64 points Basic unit Input/Output specification

| Type | Model Name | Power |  | Input | Input Point | Output | Output Point |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 24V DC | $\begin{gathered} 100 / 200 \mathrm{~V} \\ \mathrm{AC} \end{gathered}$ |  | 24V DC |  | Relay Output | Transistor Output |  | Transistor Output(source ESCP) Low Current High Current |  |
|  |  |  |  |  | (1) |  | (2) | (3) | (4) | (5) | (6) |
| 20 Points | EH-A20DR |  | $\bigcirc$ | DC $24 \mathrm{~V} \times 12$ | 12 (3)[4,4,4] | Relay $\times 8$ | $\begin{gathered} 8(5) \\ {[1,4,1,1,1]} \end{gathered}$ |  |  |  |  |
|  | EH-D20DR | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 12$ | 12 (3)[4,4,4] | Relay $\times 8$ | $\begin{gathered} 8(5) \\ {[1,4,1,1,1]} \end{gathered}$ |  |  |  |  |
|  | EH-D20DT | O |  | DC $24 \mathrm{~V} \times 12$ | 12 (3) $[4,4,4]$ | Transistor $\times 8$ (sink) |  | 4 (1) | 4 (1) |  |  |
|  | EH-D20DTPS | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 12$ | 12 (3)[4,4,4] | Transistor ESCP) $\times 8$ |  | 4 (1) |  | 4 (1) |  |
| 40 Points | EH-A40DR |  | $\bigcirc$ | DC $24 \mathrm{~V} \times 24$ | 24 (2) [8,16] | Relay $\times 16$ | $\begin{gathered} 16(6) \\ {[6,2,4,2,2, * 1]} \end{gathered}$ |  |  |  |  |
|  | EH-D40DR | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 24$ | 24 (2)[8,16] | Relay $\times 16$ | $\begin{gathered} 16(6) \\ {\left[6,2,4,2,2,{ }^{*} 1\right]} \end{gathered}$ |  |  |  |  |
|  | EH-D40DT | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 24$ | 24 (2)[8,16] | Transistor $\times 16$ (sink) |  | 4 (2)[4]** | 12 (2)[12]*1 |  |  |
|  | EH-D40DTPS | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 24$ | $24(2)[8,16]$ | $\begin{aligned} & \text { Transistor (source } \\ & \text { ESCP) } \times 16 \end{aligned}$ |  | 4 (2)[4]** |  | 12 (2)[12]*1 |  |
| 64 Points | EH-A64DR |  | $\bigcirc$ | DC $24 \mathrm{~V} \times 40$ | 40 (2) [16,24] | Relay $\times 24$ | $\begin{gathered} 24(9) \\ {[6,2,4,2,2,2,2,2,2]} \end{gathered}$ |  |  |  |  |
|  | EH-D64DR | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 40$ | 40 (2) [16,24] | Relay $\times 24$ | $\begin{gathered} 24(9) \\ {[6,2,4,2,2,2,2,2,2]} \end{gathered}$ |  |  |  |  |
|  | EH-D64DT | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 40$ | 40 (2)[16,24] | Transistor $\times 24$ (sink) |  | 4 (2)[4]** | $20(6)[8,8,4]^{*} 1$ |  |  |
|  | EH-D64DTPS | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 40$ | 40 (2)[16,24] | Transistor (source ESCP) $\times 24$ |  | 4 (2)[4]*1 |  | $16(4)[8,8]^{*} 1$ | 4 (2)[4]** |

The value of () : number of common. The value of [] : number of I/O points to each common.
*1: Although it is two common to the number of outputs of eath common, it connects inside.

| Type | Model Name | Power |  | Input | Input Point | Output | Output Point |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 24V DC | $\begin{gathered} 100 / 200 \mathrm{~V} \\ \mathrm{AC} \end{gathered}$ |  | 24V DC |  | Relay Output | Transistor Output |  | Transistor Output(source ESCP) |  |
|  |  |  |  |  | (7) |  | (8) | (3) | (4) | (5) | (6) |
| 64 Points | EH-A64EDR |  | $\bigcirc$ | DC $24 \mathrm{~V} \times 40$ | $\begin{gathered} 40(2) \\ {[16,24]} \end{gathered}$ | Relay x 24 | $\begin{gathered} 24(9) \\ {[6,2,4,2,2,2,2,2,2]} \end{gathered}$ |  |  |  |  |
|  | EH-D64EDR | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 40$ | $\begin{gathered} 40(2) \\ {[16,24]} \end{gathered}$ | Relay x 24 | $\begin{gathered} 24(9) \\ {[6,2,4,2,2,2,2,2,2]} \end{gathered}$ |  |  |  |  |
|  | EH-D64EDT | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 40$ | $\begin{aligned} & 40(2) \\ & {[16,24]} \end{aligned}$ | Transistor $\times 24$ (sink) |  | 4 (2)[4]*1 | $20(6)[8,8,4]^{* 1}$ |  |  |
|  | EH-D64EDTPS | $\bigcirc$ |  | DC $24 \mathrm{~V} \times 40$ | $\begin{gathered} 40(2) \\ {[16,24]} \end{gathered}$ | $\begin{aligned} & \text { Transistor (source } \\ & \text { ESCP) } \times 24 \end{aligned}$ |  | 4 (2)[4]*1 |  | 16 (4)[8,8]*1 | 4 (2)[4]*1 |


| Item |  |
| :---: | :---: |
| Input voltage |  |
| Allowable input voltage range |  |
| Input impedance |  |
| Input current |  |
| Operating voltage | ON voltage |
|  | OFF voltage |
| Input lag | OFF $\rightarrow$ ON |
|  | ON $\rightarrow$ OFF |
| Polarity |  |
| Insulation system |  |
| Input display |  |
| External connection |  |


| Specification |  |
| :---: | :---: |
| X0, X2, X4, X6 | Except the following |
| 24 V DC |  |
| 0 to 30V DC |  |
| Approx. $2.7 \mathrm{k} \Omega$ | Approx. $4.7 \mathrm{k} \Omega$ |
| Approx. 8 mA | Approx.4.8 mA |
| $18 \mathrm{VDC}($ min $) / 4.5 \mathrm{~mA}$ (max) | $18 \mathrm{VDC}($ min) $/ 3.3 \mathrm{~mA}($ max $)$ |
| $5 \mathrm{VDC}($ min) $/ 1.8 \mathrm{~mA}($ max $)$ | $5 \mathrm{VDC}($ max $) / 1.6 \mathrm{~mA}($ max $)$ |
| 2 to 20 ms (user | setup is possible.) |
| 2 to 20 ms (user | setup is possible.) |
| None |  |
| Photocoupler insulation |  |
| LED (Green) |  |
| Removable type screw | w terminal block (M3) |

Internal Circuit

0

(2)Relay output

| Item |  | Specification |
| :---: | :---: | :---: |
| Rated load voltage |  | 5 to 250 V AC, 5 to 30 V DC |
| Minimum switching current |  | 10 mA (5VDC) |
| Maximum | 1 circuit | 2 A (24V DC, 240V AC) |
| load current | 1 common | 5A |
| Output | OFF $\rightarrow$ ON | 15 ms (max) |
| response time | ON $\rightarrow$ OFF | $15 \mathrm{~ms} \mathrm{(max})$ |
| Surge removal circuit |  | None |
| Fuse |  | None |
| Insulation system |  | Relay insulation |
| Output display |  | LED (Green) |
| Externally supplied power (For driving relays) |  | Not used |
| Contact life ${ }^{\text {*1 }}$ |  | 20,000,000 times (mechanical) 200,000 times (electrical : 2A) |
| Insulation |  | $1,500 \mathrm{~V}$ or more (external - internal) 500 V or more (external - external) |
| External connection |  | Removable type screw terminal block (M3) |

(3)DC Transistor output

| Item | Specification <br> $24 / 12 \mathrm{~V} \mathrm{DC}$ <br> $(+10 \%,-15 \%$ |
| :--- | :---: |
| Rated load voltage | 10 mA |

(4)DC Transistor output

| Item |  |
| :--- | :--- |
| Rated load voltage |  |
| Minimum switching current |  |
| Leak current |  |
| Maximum <br> load current | 1 circuit |
| 1 common |  |
| Output <br> response time | OFF $\rightarrow$ ON |
| Surge removing circuit |  |
| Fuse |  |
| Insulation system |  |
| Output display |  |
| Externally supplied power |  |
| Insulation |  |
| Output voltage drop |  |
| External connection |  |


| Specification |
| :---: |
| 24/12 V DC (+10 \%, -15 \%) |
| 10 mA |
| 0.1 mA (max) |
| 0.5 A |
| 64-point type : $3 \mathrm{~A}, 40$-point type : 5 A , 20-point type : 2 A , |
| 0.1 ms (max) 24 V DC 0.2A |
| 0.1 ms (max) 24 V DC 0.2A |
| None |
| None |
| Photocoupler insulation |
| LED (green) |
| 12 to 30 V DC |
| $1,500 \mathrm{~V}$ or more (external-internal) 500 V or more (external-external) |
| 0.3 V DC (max) |
| Removable type screw terminal block (M3) |

Circuit diagram

Sink type


■ (5)DC Transistor output (ESCP type) ... LCDC-Low Current

© (6DC Transistor output (ESCP type) ... HCDC-High Current


Circuit diagram

Source type (ESCP)

(7)DC input ( 64 points expansion unit)

| Item |  | Specifi | cation | Circuit diagram |
| :---: | :---: | :---: | :---: | :---: |
|  |  | X0, X2, X4, X6 | Except the left |  |
| Input voltage |  | 24V DC |  |  |
| Allowable input voltage range |  | 0 to 30V DC |  |  |
| Input impedance |  | Approximately $2.7 \mathrm{k} \Omega$ | Approximately $4.7 \mathrm{k} \Omega$ |  |
| Input current |  | 8 mA typical | 4.8 mA typical |  |
| Operating voltage | ON voltage | 18 VDC (min) / 4.5mA (max) | $18 \mathrm{VDC}(\mathrm{min}) / 3.3 \mathrm{~mA}(\mathrm{max})$ |  |
|  | OFF voltage | $5 \mathrm{VDC}($ min) $/ 1.8 \mathrm{~mA}$ (max) | $5 \mathrm{VDC}(\max ) / 1.6 \mathrm{~mA}(\max )$ |  |
| Input lag | OFF $\rightarrow$ ON | 2 ms or less |  |  |
|  | ON $\rightarrow$ OFF | 2 ms or less |  |  |
| Polarity |  | None |  |  |
| Insulation system |  | Photocoupler insulation |  |  |
| External connection |  | Removable type screw terminal block (M3) |  |  |

8Relay output (64 points expansion unit)

| Item |  |
| :--- | :--- |
| Rated load voltage |  |
| Maximum 1 circuit <br> load current  | 1 common |
| Output | OFF $\rightarrow$ ON |
| response time | ON $\rightarrow$ OFF |
| Surge removing circuit |  |
| Fuse |  |
| Insulation system |  |
| External connection |  |
| Contact life |  |
|  |  |
| Insulation |  |


| Specification |
| :---: |
| 5 to $250 \mathrm{~V} \mathrm{AC}, 5$ to 30 VDC |
| $2 \mathrm{~A} \mathrm{(24V} \mathrm{DC,240V} \mathrm{AC)}$ |
| $15 \mathrm{~ms}(\max )$ |
| $15 \mathrm{~ms}(\max )$ |
| None |
| None |
| Relay insulation |
| Removable type screw terminal block (M3) |
| $20,000,000$ times (mechanical) |
| 200,000 times (electrical : 1.5A) |
| 1500 V or more (external - internal) |
| 500 V or more (external - external) |

Circuit diagram


## High speed counter

| Item |  | Single | 2-phase |
| :---: | :---: | :---: | :---: |
| Choices for counter input channels |  | X0, X2, X4, X6 | Use X0 and X2 in pair / Use X4 and X6 in pair |
| Input voltage | ON | 18 V |  |
|  | OFF | 5 V |  |
| Width of count pulse |  | $10 \mu \mathrm{~s}$ | $17 \mu \mathrm{~s}$ |
| Maximum count frequency |  | 100 kHz | 60 kHz |
| Count register |  | 16 bits / 32 bits (depend on operation mode) |  |
| Coincidence output |  | Possible (or assigned as standard output) |  |
| ON / OFF preset |  | Possible (or assigned as standard output) |  |
| Upper / lower limit setting |  | Impossible (16 bits counter : ring counter ... 0 to 65,535 )( 32 bits counter : ring counter ... 0 to $4,294,967,295$ ) |  |
| Pre-load / Strobe |  | Possible (or assigned as standard input) |  |

## Pulse train output / PWW output

| Item | Specification |
| :---: | :---: |
| Available outputs | Y100-Y103 (optional) |
| Load voltage | 12 / 24 V |
| Minimum load current | 1 mA |
| PWM max. output frequency | each channel $65,535 \mathrm{~Hz}$ |
| Pulse train max. output frequency | each channel $65,535 \mathrm{~Hz}$ |

## Interiupt Input Specifications

## Positioning expansion unit

## Features

- Positioning control or speed control is enabled by pulse train output (max. 2Mpps) if the stepping motor or servo is connected.
- 2-axes can be controlled in one positioning expansion unit. There is no interpolation function.
- 2 positioning expansion units can be connected to one basic unit.
Combination other expansion unit is also possible.
- Operating information that can store with 2 axes is 256 data. For these operating information, max. 499 continuing operations in one axis.
- Modbus RTU is used for the communication protocol. The positioning expansion unit can work without a basic unit using communication of modbus RTU.
- The tool to be able to set various parameters easily was prepared.

Note : Positioning expansion unit is supported by 20/23/28/40/64 basic unit.


Basic unit produced before March 2008 cannot be used for expansion unit.

## Functional specifications

| Item |  |
| :---: | :---: |
| Number of axes |  |
| Maximum velocity |  |
| Positioning system | Move type |
|  | Position rollover |
|  | Positioning instruction unit |
|  | Speed instruction range *1 |
|  | Acceleration and deceleration |
|  | Dwell time |
|  | Acc/Dec rate *2 |
|  | Backlash revision |
|  | Range |
|  | Pulse output type |
|  | Pulse output method |
| Positioning data | Number of memorable data |
|  | Setting method |
| Operation mode |  |
| Homing function |  |
| Manual (JOG) operation |  |
| Auto operation |  |
| Feedrate override function |  |
| //0 assignment |  |
| Communication function *3 | Protocol |
|  | Transmission speed |


| Specifications |
| :---: |
| 2 axes |
| 2M pulses/s |
| (1) Absolute + Increment method (2) Increment method |
| Linear, rotation |
| Pulse, $\propto \mathrm{m}$, inch, degree, Free-form |
| 1 to 2M pulse/s |
| Linear Acc/Dec, S-shaped Acc/Dec |
| 0 to $32,768 \mathrm{~ms}$ (1 ms unit) |
| 1 to $50,000,000$ (pulse $/ \mathrm{s}^{2}, \propto \mathrm{~m} / \mathrm{s}^{2}$, inch $/ \mathrm{s}^{2}$, degree $/ \mathrm{s}^{2}$, Free-form $/ \mathrm{s}^{2}$ ) |
| 0 to 65,535 (pulse, $\propto \mathrm{m}$, inch, degree, Free-form) |
| +2,147,463,647 to $-2,147,463,648$ pulse |
| (1) Pulse train [CW / CCW] |
| Line driver output |
| 256 (non-volatility) |
| Sequence program from PLC and personal computer |
| Auto operation, manual operation |
| Free homing, Low-speed homing, High-speed homing 1 (OFF edge), High-speed homing 2 (marker stop) |
| Pulse output by manual input signal or command |
| Pulse output according to profile data registered with sequence table. |
| 1 to 100\% (Speed scale rate, 1\% unit) |
| Word X 8W / Word Y 8W <br> (Positioning expansion unit uses assignment for two expansion units.) |
| Modbus RTU |
| 9600, 19200, 57600, 115200bps |

[^3]Number of I/O No. (Input/Output register) become either of four pattern shown below.


Input register is WXu00-Wxu07(u:unit No.). Output register is WYu'00 - WYu'07(u':unit No.).

## Thermocouple Expansion Unit

## Input Specifications

| Item |  |
| :---: | :---: |
| No. of channels |  |
| Supported thermocouple |  |
| Each type of specification (Ambient temp. 0 to $55{ }^{\circ} \mathrm{C}$ ) |  Type |
|  | K |
|  | J |
|  | E |
|  | S |
|  | T |
|  | B |
|  | N |
|  | 50 mV |
|  | 100mV |
| Conversion data |  |
| Isolation B <br>   <br>  B <br> ci  | Between channels |
|  | Between channel and internal circuit |
| Cold junction temperature input range |  |
| Cold junction temperature compensation |  |
| Diagnostic error (Over flow or breaking wire) |  |
| Conversion time (4 channels all) |  |
| External wiring length (*2) |  |


| Specification |  |  |  |
| :---: | :---: | :---: | :---: |
| 4 channels |  |  |  |
| Type K, J, E, S, T, B, N |  |  |  |
| Accuracy guaranteed range | accuracy (*1) | Resolution | Input range |
| -200 to $1200{ }^{\circ} \mathrm{C}$ | $\pm 0.4 \%$ (FS) | $0.1{ }^{\circ} \mathrm{C} / 0.2$ | -270 to $1370{ }^{\circ} \mathrm{C}$ |
| -40 to $750{ }^{\circ} \mathrm{C}$ | $\pm 0.3 \%$ (FS) | $0.1{ }^{\circ} \mathrm{C} / 0.2$ | -270 to $1200{ }^{\circ} \mathrm{C}$ |
| -200 to $900{ }^{\circ} \mathrm{C}$ | $\pm 0.3 \%$ (FS) | $0.1{ }^{\circ} \mathrm{C} / 0.2$ | -270 to $1000{ }^{\circ} \mathrm{C}$ |
| 0 to $1600{ }^{\circ} \mathrm{C}$ | $\pm 1.0 \%$ (FS) | $1.0{ }^{\circ} \mathrm{C} / 2.0$ | -50 to $1760{ }^{\circ} \mathrm{C}$ |
| -200 to $350{ }^{\circ} \mathrm{C}$ | $\pm 0.8 \%$ (FS) | $0.1{ }^{\circ} \mathrm{C} / 0.2$ | -270 to $400{ }^{\circ} \mathrm{C}$ |
| 600 to $1700{ }^{\circ} \mathrm{C}$ | $\pm 1.0 \%$ (FS) | $1.0{ }^{\circ} \mathrm{C} / 2.0$ | 0 to $1820{ }^{\circ} \mathrm{C}$ |
| -200 to $1200{ }^{\circ} \mathrm{C}$ | $\pm 0.4 \%$ (FS) | $0.1{ }^{\circ} \mathrm{C} / 0.2$ | -270 to $1300{ }^{\circ} \mathrm{C}$ |
| -50 to 50 mV | $\pm 0.5 \%$ (FS) | 0.01 mV | -50 to 50 mV |
| -100 to 100 mV | $\pm 0.5 \%$ (FS) | 0.02 mV | -100 to 100mV |
| 15 bits + sign ( $0.1{ }^{\circ} \mathrm{C} / 0.1 / 0.01 \mathrm{mV}$ ) |  |  |  |
| Not isolated |  |  |  |
| Isolated by photo coupler |  |  |  |
| -20 to $80{ }^{\circ} \mathrm{C}$ |  |  |  |
| $\pm 2{ }^{\circ} \mathrm{C}$ or less (ambient temp. 0 to $55{ }^{\circ} \mathrm{C}$ ) |  |  |  |
| Conversion data: H7FFF (LED blinks at error channel) |  |  |  |
| 563 msec ( thermocouple) / 141 msec ( mV ) |  |  |  |
| Max. 100 m |  |  |  |

 condition of 10 minutes after power ON.
*2: Note : The max. cable length is 100 m , however it depends on noisy environment or other conditions.

## Analog output Specifications ( EH-D6ETC only )

| Item | Specification |
| :--- | :---: |
| No. of analog output | 2 channels, single output |
| Output Ranges (Selected by DIP switch) | $0-10 \mathrm{~V}(10.23 \mathrm{~V} \mathrm{Max.)/0-20mA(20.48mA} \mathrm{Max)}. \mathbf{1 2 ~ B i t s}$ |
| Resolution | $\pm 1 \%$ of full scale over temp. range |
| Accuracy | 8.8 ms |
| Conversion time | Output load range and max. voltage <br> Output capacitance and inductance |
| Current outputs | 10 to $500 \Omega, 10 \mathrm{~V}$ |
| Voltage outputs | Output load range <br> Output load inductance |

## 20/40/64 points type Option hoard Specilications

| No. | Type |  |
| :---: | :---: | :--- |
| 1 | EH-OBMEM | Memory board |
| 2 | EH-OB232 | RS-232C Communication board |
| 3 | EH-OB485 | RS-422/485 Communication board |
| 4 | EH-OBUSB | USB board |

Backup of a user program and the special internal output for a setup of special function. RS-232C serial communication port, Analog input 2ch
RS-422 / 485 serial communication port, Analog input 2ch
USB communication port

## (1)Memory board

\section*{| Item | Spec |
| :--- | ---: |
| Memory capacity | 16 ksteps |
| Size | $19 \times 41.5$ |
| (2)RS-232C Communication board |  |
| RS-232C port Specification |  |}


| Item | Specification |
| :--- | :---: |
| Number of port | 1 |
| Cable length | Max. 15 m |
| Communication system | Half duplex |
| Baud rate | $4,800-38,400$ pos(Dedicated port)300-57,600bos(General-purpose port) |
| Connection mode | Hi-Protocol(procedure1/2) / |
| Non-Protocol |  |
| Protocol |  |



Analog Input Specification

| Item | Specification |
| :--- | :---: |
| No. of input | 2 ch. |
| Input range | $0-10 \mathrm{~V}(10.24 \mathrm{~V}$ max. $)$ |
| Accuracy | $\pm 1 \%$ of full cale |
| Resolution | 10 bits |
| Input impedance | $100 \mathrm{k} \Omega$ |
| Isolation between channels | Not isolated |
| Isolation between CPU and analog signal | Not isolated |

## (3)RS-422/485 Communication board RS-422 / 485 port Specification

| Item | Specification |
| :--- | :---: |
| Number of port | 1 |
| Cable length | Max. 500 m |
| Communication system | Half duplex |
| Baud rate | $4,800-38,400$ bos(Dedicated port) 300 $-57,600$ pos(General-purpose port) |
| Connection mode | $1: \mathrm{N}($ Max. |
| Protocol | Hi-Protocol(procedure1/2) $/$ / |



Analog Input Specification

| Item | Specification |
| :--- | :---: |
| No. of input | 2 ch. |
| Input range | $0-10 \mathrm{~V}(10.24 \mathrm{~V}$ max. $)$ |
| Accuracy | $\pm 1 \%$ of full cale |
| Resolution | 10 bits |
| Input impedance | $100 \mathrm{k} \Omega$ |
| Isolation between channels | Not isolated |
| Isolation between CPU and analog signal | Not isolated |

(4)USB board

| Item | Specification |
| :--- | :---: |
| Function | USB 232C conversion |
| USB version | Correspond USB 2.0 |
| Connector | Straight B type |
| Power | BUS power |
| Connection mode | $1: 1$ |
| COM port Driver | Download from FTDI |



Since this board is a converter from RS-232C to USB, the USB port of PC must be regarded as RS-232C port. For this reason, COM port driver is necessary for your PC. Please download the driver from following URL and install so that USB port works as serial port.

## IO ASSIENIMENTI

Basic unit / expansion unit

| Unit |  |  | I/O Classification | 10 - point type | 14 - point type | 20 - point type | 23 - point type | 28 - point type | 40 - point type | 64 - point type |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Basic <br> Unit | Digital | Input | Slot 0 : X48 | X0~5 | $\mathrm{XO} \sim 7$ | $\mathrm{XO} \sim 11$ | $\mathrm{XO} \sim 12$ | X0~15 | $\mathrm{XO} \sim 23$ | X0~39 |
|  |  | Output | Solt 1 : Y32 | Y100~103 | Y100~105 | Y100~107 | Y100~109 | Y100~111 | Y100~115 | Y100~123 |
|  |  |  | Slot 2 : empty 16 | - | - | - | - | - | - | - |
|  | Analog | Input | Slot 3 : X4W | - | - | - | WX30~31 | - | - | - |
|  |  | Output | Slot 4 : Y4W | - | - | - | WY40 | - | - | - |
| Expansion Unit 1 | Digital | Input | Unit 1 / Slot0 : B1/1 | - | X1000~1015 |  |  |  |  |  |
|  |  | Output |  | - | Y1016~1031 |  |  |  |  |  |
|  | Analog | Input | Unit 1 / Slot0 :FUN0 | - | WX101~10 |  |  |  |  |  |
|  |  | Output |  | - | WY106~107 |  |  |  |  |  |
| Expansion Unit 2 | Digital | Input | Unit 2 / Slot0 : B1/1 | - | X2000~2015 |  |  |  |  |  |
|  |  | Output |  | - | Y2016~2031 |  |  |  |  |  |
|  | Analog | Input | Unit 2 / Slot0 :FUN0 | - | WX201~204 |  |  |  |  |  |
|  |  | Output |  | - | WY206~207 |  |  |  |  |  |
| Expansion Unit 3 | Digital | Input | Unit 3 / Slot0 : B1/1 | - | X3000~3015 |  |  |  |  |  |
|  |  | Output |  | - | Y3016~3031 |  |  |  |  |  |
|  | Analog | Input | Unit 3 / Slot0 :FUNO | - | WX301~304 |  |  |  |  |  |
|  |  | Output |  | - | WY306~307 |  |  |  |  |  |
| Expansion Unit 4 | Digital | Input | Unit 4 / Slot0 : B1/1 | - | X4000~4015 |  |  |  |  |  |
|  |  | Output |  | - | Y4016~4031 |  |  |  |  |  |
|  | Analog | Input | Unit 4 / Slot0 :FUNO | - | WX401~404 |  |  |  |  |  |
|  |  | Output |  | - | WY406~407 |  |  |  |  |  |

## 64-points expansion unit

| Unit |  |  | I/O Classification | 10 - point type | 14 - point type | 20 - point type | 23 - point type | 28 - point type | 40 -point type | 64 - point type |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Expansion Unit 1 | Digital | Input | Slot 0 : X48 | - | X1000~1039 |  |  |  |  |  |
|  |  |  | Solt 1 : Y32 | - | Y1100~1123 |  |  |  |  |  |
|  |  |  | Slot 2 : empty 16 | - | - | - | - | - | - | - |
| Expansion Unit 2 | Digital | Input | Slot 0 : X48 | - | X2000~2039 |  |  |  |  |  |
|  |  | Output | Solt 1 : Y32 | - | Y2100~2123 |  |  |  |  |  |
|  |  |  | Slot 2 : empty 16 | - | - | - | - | - | - | - |
| Expansion Unit 3 | Digital | Input | Slot 0 : X48 | - |  |  | X30 | 0~3039 |  |  |
|  |  | Output | Solt 1 : Y32 | - | Y3100~3123 |  |  |  |  |  |
|  |  |  | Slot 2 : empty 16 | - | - | - | - | - | - | - |
| Expansion Unit 4 | Digital | Input | Slot 0 : X48 | - | $\mathrm{X} 4000 \sim 4039$$\mathrm{Y} 4100 \sim 4123$ |  |  |  |  |  |
|  |  | Output | Solt 1 : Y32 | - |  |  |  |  |  |  |
|  |  |  | Slot 2 : empty 16 | - | - | - | - | - | - | - |

## High speed counter, Pulse train output and PWM output of MICRO-EH

## MICRO-EH can perform easily simple positioning control by Pulse train output, and speed control by the PWM output. - Simple positioning control

With DC (transistor) output type, a pulse train output is possible.
MICRO-EH can perform positioning control of a stepping motor etc. by combining a High-speed counter input and a pulse train output.


With using PWM output function, MICRO-EH can perform speed control of DC motor instead of conventional control by the analog output.


## MICRO-EH

| No. | Classification | Model Name | Specifications |  |  |  | Weight(g) | Power Consumption (A) |  |  | Standard Compliance |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  | 100 V AC | 264 V AC | 24 V DC |  |  |  |
|  |  |  | Power | Input | Output | Remarks |  | Normal | Normal | Normal | CE | UL | C-Tick |
| 1 | 10 Points | EH-D10DT | 24V DC | 24 V DC $\times 6$ | Transistor $\times 4$ | Sink |  | 200 | - | - | 0.12 | $\bigcirc$ | O | O |
| 2 |  | EH-D10DTP | 24V DC | 24 V DC $\times 6$ | Transistor $\times 4$ | Source | 200 | - | - | 0.12 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 3 |  | EH-D10DR | 24V DC | 24 V DC $\times 6$ | Relay $\times 4$ |  | 200 | - | - | 0.12 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 4 | 14 Points | EH-D14DT | 24V DC | 24 V DC $\times 8$ | Transistor $\times 6$ | Sink | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 5 |  | EH-D14DTP | 24V DC | 24 V DC $\times 8$ | Transistor $\times 6$ | Source | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 6 |  | EH-D14DTPS | 24V DC | 24 V DC $\times 8$ | Transistor x 6 (short circuit protection) | Source | 300 | - | - | 0.16 | $\bigcirc$ | - | $\bigcirc$ |
| 7 |  | EH-D14DR | 24 V DC | 24 V DC $\times 8$ | Relay $\times 6$ |  | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 8 |  | EH-A14DR | 100/200 V AC | 24 V DC $\times 8$ | Relay $\times 6$ |  | 400 | 0.1 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 9 |  | EH-A14AS | 100/200 V AC | AC $\times 8$ | SSR $\times 6$ |  | 380 | 0.1 | 0.06 | - | O | $\bigcirc$ | O |
| 10 | 20 Points | EH-D20DT | 24V DC | 24 V DC $\times 12$ | Transistor $\times 8$ | Sink | 450 | - | - | 0.18 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 11 |  | EH-D20DTPS | 24V DC | 24 V DC $\times 12$ | Transistor x 8 (short circuit protection) | Souse | 450 | - | - | 0.18 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 12 |  | EH-D20DR | 24 V DC | 24 V DC $\times 12$ | Relay $\times 8$ |  | 470 | - | - | 0.22 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 13 |  | EH-A20DR | 100/200V AC | 24 V DC $\times 12$ | Relay $\times 8$ |  | 550 | 0.12 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 14 | 23 Points | EH-D23DRP | 24V DC | $\begin{aligned} & 24 \mathrm{~V} \text { DC } \times 13 \\ & \text { Analog } \times 2 \end{aligned}$ | Relay $\times 9$ <br> Transistor x 1 <br> Analog $x 1$ | Source | 500 | - | - | 0.3 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 15 |  | EH-A23DRP | 100/200 V AC | $\begin{aligned} & 24 \mathrm{~V} D \mathrm{D} \times 13 \\ & \text { Analog } \times 2 \end{aligned}$ | Relay $\times 9$ <br> Transistor $\times 1$ <br> Analog $x 1$ | Source | 600 | 0.2 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 16 |  | EH-A23DR | 100/200 V AC | $\begin{aligned} & 24 \mathrm{~V} D C \times 13 \\ & \text { Analog } \times 2 \end{aligned}$ | $\begin{aligned} & \text { Relay } \times 10 \\ & \text { Analog } \times 1 \end{aligned}$ |  | 600 | 0.2 | 0.06 | - | $\bigcirc$ | - | $\bigcirc$ |
| 17 | 28 Points | EH-D28DT | 24V DC | 24 V DC $\times 16$ | Transistor x 12 | Sink | 500 | - | - | 0.2 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 18 |  | EH-D28DTP | 24V DC | 24 V DC $\times 16$ | Transistor $\times 12$ | Source | 500 | - | - | 0.2 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 19 |  | EH-D28DTPS | 24V DC | 24 V DC $\times 16$ | Transistor x 12 (short circuit protection) | Source | 500 | - | - | 0.2 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 20 |  | EH-D28DRP | 24V DC | 24 V DC $\times 16$ | Relay x 11 <br> Transistor $\times 1$ | Source | 500 | - | - | 0.3 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 21 |  | EH-D28DR | 24 V DC | 24 V DC $\times 16$ | Relay $\times 12$ |  | 500 | - | - | 0.3 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 22 |  | EH-A28DRP | 100/200 V AC | 24 V DC $\times 16$ | Relay $\times 11$ <br> Transistor x 1 | Source | 600 | 0.2 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 23 |  | EH-A28DR | 100/200 V AC | 24 V DC $\times 16$ | Relay x 12 |  | 600 | 0.2 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 24 |  | EH-A28AR | 100/200 V AC | AC $\times 16$ | Relay $\times 12$ |  | 500 | 0.2 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 25 |  | EH-A28AS | 100/200 V AC | AC $\times 16$ | SSR $\times 12$ |  | 600 | 0.2 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 26 | 40Points | EH-D40DT | 24 V DC | 24 V DC $\times 24$ | Transistor $\times 16$ | Sink | 450 | - | - | 0.24 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 27 |  | EH-D40DTPS | 24V DC | 24 V DC $\times 24$ | Transistor x 12 (short circuit protection) | Souse | 450 | - | - | 0.24 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 28 |  | EH-D40DR | 24 V DC | 24 V DC $\times 24$ | Relay $\times 16$ |  | 480 | - | - | 0.32 | $\bigcirc$ | $\bigcirc$ | O |
| 29 |  | EH-A40DR | 100/200 V AC | 24 V DC $\times 24$ | Relay $\times 16$ |  | 560 | 0.15 | 0.08 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 30 | 64 Points | EH-D64DR | 24V DC | 24 V DC $\times 40$ | Relay $\times 24$ |  | 640 | - | - | 0.5 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 31 |  | EH-D64DT | 24V DC | 24 V DC $\times 40$ | Transistor x 24 | Sink | 640 | - | - | 0.5 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 32 |  | EH-D64DTPS | 24V DC | 24 V DC $\times 40$ | Transistor x 24 (short circuit protection) | Source | 640 | - | - | 0.5 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 33 |  | EH-A64DR | 100/200 V AC | 24 V DC $\times 40$ | Relay $\times 24$ |  | 720 | 0.4 | 0.2 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 34 | 8 Points Expansion unit | EH-D8ED | 24V DC | 24 V DC $\times 8$ | - |  | 260 | - | - | 0.07 | $\bigcirc$ | $\bigcirc$ | O |
| 35 |  | EH-D8ER | 24V DC | - | Relay $\times 8$ |  | 280 | - | - | 0.06 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 36 |  | EH-D8ETPS | 24V DC | - | Transistor $\times 8$ (short circuit protection) | Source | 260 | - | - | 0.03 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 37 |  | EH-D8ET | 24 V DC | - | Transistor $\times 8$ | Sink | 260 | - | - | 0.02 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 38 |  | EH-D8EDR | 24V DC | 24 V DC $\times 4$ | Relay $\times 4$ |  | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 39 |  | EH-D8EDTPS | 24V DC | 24 V DC $\times 4$ | Transistor x4 (short circuit protection) | Source | 260 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 40 |  | EH-D8EDT | 24 V DC | 24 V DC $\times 4$ | Transistor $\times 4$ | Sink | 260 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 41 | 14 Points Expansion unit | EH-D14EDT | 24V DC | 24 V DC $\times 8$ | Transistor $\times 6$ | Sink | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 42 |  | EH-D14EDTP | 24V DC | 24 V DC $\times 8$ | Transistor $\times 6$ | Source | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 43 |  | EH-D14EDR | 24V DC | 24 V DC $\times 8$ | Relay $\times 6$ |  | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 44 |  | EH-D14EDTPS | 24V DC | 24 V DC $\times 8$ | Transistor x 6 (short circuit protection) | Source | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 45 |  | EH-A14EDR | 100/200 V AC | 24 V DC $\times 8$ | Relay $\times 6$ |  | 400 | 0.1 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 46 | 16 Points Expansion unit | EH-D16ED | 24V DC | 24 V DC $\times 16$ | - |  | 260 | - | - | 0.13 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
|  |  | EH-D16ER | 24 V DC | - | Relay $\times 16$ |  | 300 | - | - | 0.11 | $\bigcirc$ | $\bigcirc$ | O |
| 48 |  | EH-D16ETPS | 24V DC | - | Transistor x 16 (short circuit protection) | Source | 260 | - | - | 0.04 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 49 |  | EH-D16ET | 24V DC | - | Transistor x 16 | Sink | 260 | - | - | 0.03 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 50 | 28 Points Expansion unit | EH-D28EDT | 24 V DC | 24 V DC $\times 16$ | Transistor $\times 12$ | Sink | 500 | - | - | 0.2 | $\bigcirc$ | - | - |
| 51 |  | EH-D28EDTP | 24V DC | 24 V DC $\times 16$ | Transistor $\times 12$ | Source | 500 | - | - | 0.2 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 52 |  | EH-D28EDTPS | 24V DC | 24 V DC $\times 16$ | Transistor x 12 (short circuit protection) | Source | 500 | - | - | 0.2 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 53 |  | EH-D28EDR | 24V DC | 24 V DC $\times 16$ | Relay $\times 12$ |  | 500 | - | - | 0.3 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 54 |  | EH-A28EDR | 100/200 V AC | 24 V DC $\times 16$ | Relay $\times 12$ |  | 600 | 0.2 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 55 | 64 Points Expansion unit | EH-A64EDR | 100/200 V AC | 24 V DC $\times 40$ | Relay $\times 24$ |  | 720 | 0.2 | 0.1 | - | $\bigcirc$ | ※ | $\bigcirc$ |
| 56 |  | EH-D64EDR | 24V DC | 24 V DC $\times 40$ | Relay $\times 24$ |  | 640 | - | - | 0.5 | $\bigcirc$ | ※ | $\bigcirc$ |
| 57 |  | EH-D64EDT | 24 V DC | 24 V DC $\times 40$ | Transistor $\times 24$ | Sink | 640 | - | - | 0.4 | $\bigcirc$ | ※ | $\bigcirc$ |
| 58 |  | EH-D64EDTPS | 24V DC | 24 V DC $\times 40$ | Transistor $\times 24$ (short circuit protection) | Source | 640 | - | - | 0.4 | $\bigcirc$ | ※ | $\bigcirc$ |

[^4]
## MICRO-EH

| No. | Classification | Model Name | Specifications |  |  |  | Weight(g) | Power Consumption ( A ) |  |  | Standard Compliance |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  | 100 V AC | 264 V AC | 24 V DC |  |  |  |
|  |  |  | Power | Input | Output | Remarks |  | Normal | Normal | Normal | CE | UL | C-Tick |
| 59 | AnalogExpansion unit | EH-D6EAN | 24V DC | Analog $\times 4$ | Analog $\times 2$ |  |  | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | O |
| 60 |  | EH-A6EAN | 100/200 V AC | Analog $\times 4$ | Analog x 2 |  | 400 | 0.1 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 61 | RTD <br> Expansion unit | EH-A6ERTD | 100/200 V AC | RTD $\times 4$ | Analog $\times 2$ |  | 400 | 0.1 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 62 |  | EH-A4ERTD | 100/200 V AC | RTD $\times 4$ | - |  | 400 | 0.1 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 63 |  | EH-D6ERTD | 24V DC | RTD $\times 4$ | Analog x 2 |  | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 64 |  | EH-D4ERTD | 24V DC | RTD $\times 4$ | - |  | 300 | - | - | 0.16 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 65 | Thermocouple Expansion unit | EH-D6ETC | 24V DC | Thermocouple $\times 4$ | Analog x 2 |  | 300 | - | - | 0.11 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 66 |  | EH-D4ETC | 24V DC | Thermocouple $\times 4$ | - |  | 300 | - | - | 0.07 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 67 | PositioningExpansion unit | EH-D2EP | 24 V DC | 2 -axes positio | g, Pulse output: up to 2 MHz | released soon | 440 | - | - | 0.26 | $\bigcirc$ | $\bigcirc$ | O |
| 68 |  | EH-A2EP | 100/200 V AC | 2 -axes positio | g, Pulse output: up to 2 MHz | released soon | 520 | 0.12 | 0.06 | - | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 69 | Option board for 20/40/64-point type | EH-OB232 | RS-232 Communication board with Analog Input 2ch (10bit) |  |  |  |  |  |  |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 70 |  | EH-OBMEM | Memory board (16k steps) |  |  |  |  |  |  |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 71 |  | EH-OB485 | RS-422/485 Communication board with Analog Input 2ch (10bit) |  |  |  |  |  |  |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 72 |  | EH-OBUSB | USB RS-232C conversion board |  |  |  |  |  |  |  | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 73 | Expansion cable | EH-MCB10 | 1.0 m |  |  |  |  |  |  |  | n/a | n/a | n/a |
| 74 |  | EH-MCB05 | 0.5 m |  |  |  |  |  |  |  | n/a | n/a | n/a |
| 75 |  | EH-MCB01 | 0.1 m |  |  |  |  |  |  |  | n/a | n/a | n/a |
| 76 | Lithium battery | EH-MBAT | For data memory back-up |  |  | For 2328-point type | - | - | - | - | n/a | n/a | n/a |
| 77 |  | EH-MBATL | For data memory back-up (Long Type) |  |  | For 2044064-point type |  |  |  |  | n/a | n/a | n/a |
| 78 |  | EH-MBATLC |  |  |  | For 23128-point type |  |  |  |  | n/a | n/a | n/a |
| 79 | Programmingsoftware | HLW-PCRE | LADDER EDITOR for Windows ${ }^{\text {® }}$ |  |  |  |  |  |  |  | n/a | n/a | n/a |
| 80 |  | EH-MLWE | LADDER EDITOR MICRO for Winodws ${ }^{\text {® }}$ |  |  |  |  |  |  |  | n/a | n/a | n/a |
| 81 |  | HL-AT3E | LADDER EDITOR DOS version |  |  |  |  |  |  |  | n/a | n/a | n/a |
| 82 | Connection cable | EH-vCB02 | Direct connection between MICRO-EH/EH-150 and personal computer (2m) |  |  |  |  |  |  |  | n/a | n/a | n/a |
| 83 |  | WVCB02H | Connection with personal computer, EH-RS05 is required. <br> Adapter cable for WVCB02H |  |  |  |  |  |  |  | n/a | n/a | n/a |
| 84 |  | EH-RS05 |  |  |  |  |  |  |  |  | n/a | n/a | n/a |

*1: 1 piece of 0.1 m expansion cable is attached to each expansion unit
*2: Windows is a registered trademark of Microsoft Corp. in the U.S. and other countries.

## General Specifications

| Item | Specification |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Power supply type | $\begin{gathered} \text { AC } \\ \text { 100/110/120 V AC }(50 / 60 \mathrm{~Hz}), \\ 200 / 220 / 240 \mathrm{~V} \mathrm{AC}(50 / 60 \mathrm{~Hz}) \end{gathered}$ |  | DC |  |
| Power voltage |  |  | 24 V DC |  |
| Power voltage fluctuation | 85 to 264 V AC wide range |  | 19.2 to 30 V DC |  |
| range <br> Allowable momentary power failure | 85 to 100 V AC: $100 \text { to } 264 \mathrm{~V} \mathrm{AC}$ | For a momentary power failure of less than 10 ms , operation continues For a momentary power failure of less than 20 ms , operation continues | 19.2 to 30 V DC | For a momentary power failure of less than 10 ms , operation continues |
| Operating ambient temp. | 0 to $55^{\circ} \mathrm{C}$ |  |  |  |
| Storage ambient temp. | -10 to $75{ }^{\circ} \mathrm{C}$ |  |  |  |
| Operating ambient humidity | 5 to $95 \% \mathrm{RH}$ (no condensation) |  |  |  |
| Storage ambient humidity | 5 to $95 \% \mathrm{RH}$ (no condensation) |  |  |  |
| Vibration proof | Conforming to IEC (EN) 61131-2 |  |  |  |
| Noise resistance | O Noise voltage $1,500 \mathrm{Vpp}$ Noise pulse width $100 \mathrm{~ns}, 1 \mu \mathrm{~s}$ (Noise created by the noise simulator is applied across the power supply module's input terminals. This is determined by our measuring method.)Based on NEMA ICS 3-304Static noise: $3,000 \mathrm{~V}$ at metal exposed areaConforms with EN50081-2 and EN50082-2 |  |  |  |
| Supported standards | Conforms with UL, CE markings and C-TICK |  |  |  |
| Insulation resistance Dielectric withstand voltage | $20 \mathrm{M} \Omega$ or more between the AC external terminal and the protection earth (PE) terminal (based on 500 V DC megger) |  |  |  |
| Grounding | $1,500 \mathrm{~V} \mathrm{AC}$ for one minute between the AC external terminal and the protection earth (PE) terminal |  |  |  |
| Environment used | Class D dedicated grounding (grounded by a power supply module) |  |  |  |
| Structure | No corrosive gases and no excessive dirt |  |  |  |
| Cooling | Attached on an open wall |  |  |  |
| Specification | Natural air cooling |  |  |  |

## DIMENSIONS

10-point type


20/40-point type


64-point type

[Unit : mm]

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[^0]:    ■EH-MCB01: For placement of an expansion unit next to a basic unit, 10 cm long
    ( 1 piece of 10 cm expansion cable is attached to each expansion unit.)
    ■EH-MCB05: For vertical arrangement of the MICRO-EH, 50 cm long
    EEH-MCB10: For more flexible arrangement, 1 m long

[^1]:    *1: The same numbers cannot be used with the timer counter.
    *2: Only timers numbered 0 to 63 can use 0.01 s for their timer base.

[^2]:    The value of ( ): number of common. The value of [ ]:number of I/O points to each common.

[^3]:    *1: Minimum unit for speed depends on "Max. velocity" set to the common parameter.
    2: Settable ranges for acceleration and deceleration depend on "Max. velocity" set to the common parameter.
    *3: Communication board for MICRO-EH (20/40/60-point types) is required for communication.

[^4]:    $1: 1$ piece of 0.1 m expansion cable is attached to each expansion unit
    *2: Windows is a registered trademark of Microsoft Corp. in the U.S. and other countries.

